

Real-Time Scheduling

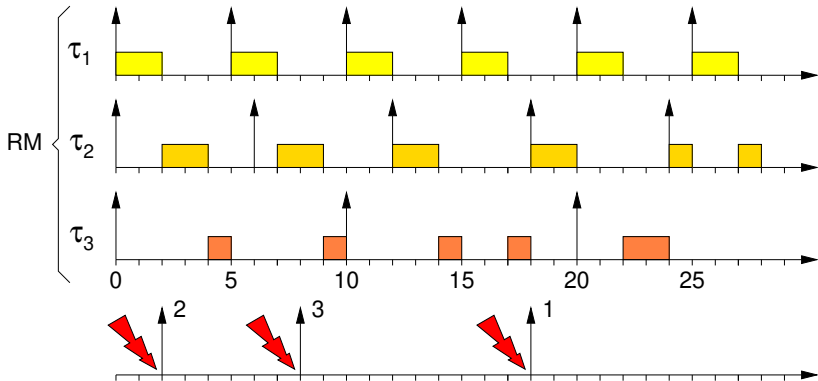
Aperiodic tasks

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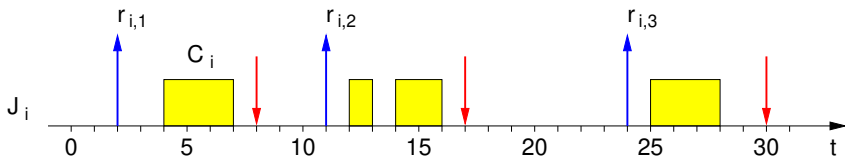
<http://robot.unipv.it/toolleeo>

Aperiodic tasks: task model



- when aperiodic requests need to be scheduled
- guarantees on periodic tasks

Aperiodic tasks



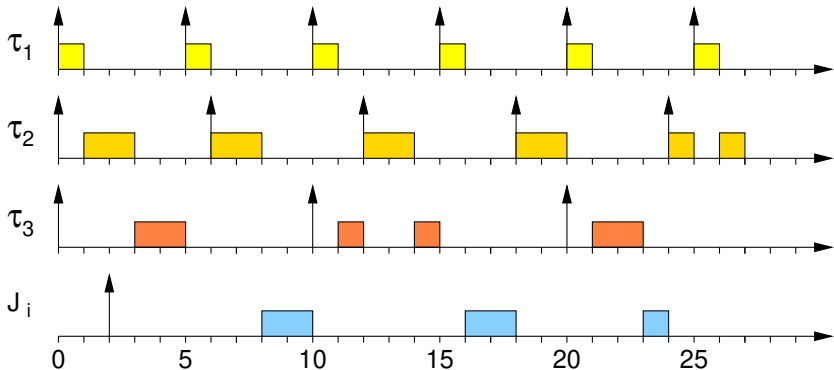
aperiodic tasks

$$r_{i,k+1} > r_{i,k}$$

sporadic tasks

$$r_{i,k+1} \geq r_{i,k} + T_i$$

Background scheduling



- aperiodic tasks are scheduled when the **processor is idle**
- simple and easy-to-implement technique

Dedicated methods

different methods have been proposed, distinguishing between **static** and **dynamic** priority assignment

considered algorithms:

Static priorities

- Polling Server
- Sporadic Server

Dynamic priorities

- Total Bandwidth Server
- Constant Bandwidth Server

Polling Server

scheduling of soft aperiodic tasks concurrently with
hard periodic tasks

assumptions:

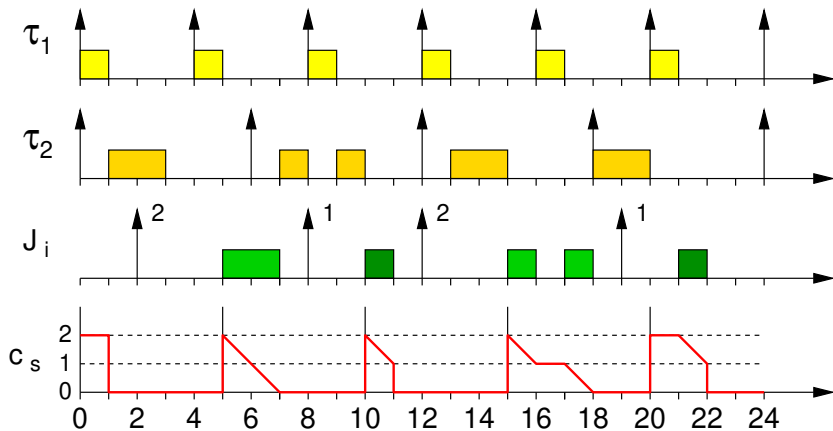
- full-preemption
- periodic tasks are scheduled by RM
- implicit deadlines
- aperiodic tasks have
 - unknown arrival time
 - known worst-case computation time

Polling Server

- 1 **period** T_s , **nominal capacity** C_s and **current capacity** c_s
- 2 every T_s time units the current capacity is recharged up to the nominal value C_s (i.e., $c_s = C_s$)
- 3 one unit of c_s is consumed for each slot served to an aperiodic task
- 4 if there are no aperiodic tasks ready for execution, the server self-suspends and flushes its current capacity (i.e., $c_s = 0$)

the flushing of the capacity may cause the presence of idle times that is not exploitable by aperiodic tasks ready for execution

Polling Server



$$\tau_1 = (1, 4)$$

$$\tau_2 = (2, 6)$$

$$C_s = 2 \text{ e } T_s = 5$$

Schedulability analysis

from the schedulability viewpoint, a Polling Server behaves like a periodic task having period T_s and WCET C_s

$$U_p + U_s \leq U_{lub}(n + 1)$$

$$\sum_{i=1}^n \frac{C_i}{T_i} + \frac{C_s}{T_s} \leq (n + 1) \left[2^{1/(n+1)} - 1 \right]$$

in case there are m Polling Servers:

$$U_p + \sum_{j=1}^m U_{s_j} \leq U_{lub}(n + m)$$

Sporadic Server

parameters for its definition:

- period T_s
- maximum budget C_s
- static priority P_s (e.g., set according to RM)

parameters used for its functioning:

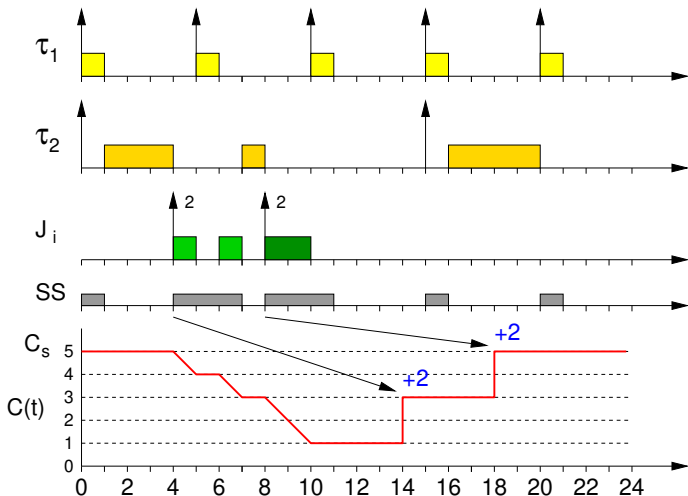
- $C(t)$: current server capacity
- P_{exe} : priority of the running task

Sporadic Server: operating rules

the Sporadic Server works according to the following rules:

- 1 the server is said **active** at time t if $P_{exe} \geq P_s$ and $C(t) > 0$
- 2 the server is said **idle** at time t if $P_{exe} < P_s$ or $C(t) = 0$
- 3 at time $t = 0$ the server is idle and $C(0) = C_s$
- 4 when the server becomes active at time t_1 a corresponding recharging time is set at time $t_r = (t_1 + T_s)$
- 5 when the server becomes idle at time $t_2 > t_1$ a recharge budget is set equal to the budget C_r consumed during the interval $[t_1, t_2)$
- 6 at time t_r the capacity C_r is added to the current budget

Sporadic Server: example



$$\tau_1 = (1, 5)$$

$$\tau_2 = (4, 15)$$

$$C_s = 5 \text{ e } T_s = 10$$

SS: schedulability analysis

a Sporadic Server **does not behave like a periodic task**

$$\sum_{i=1}^n \frac{C_i}{T_i} \leq n \left[\left(\frac{2}{U_s + 1} \right)^{1/n} - 1 \right]$$

- let U_p be the utilization of all periodic tasks
- the highest utilization of the sporadic server that guarantees the schedulability of periodic tasks is U_{SS}^*

$$U_{SS}^* = 2 \left(\frac{U_p}{n} + 1 \right)^{-n} - 1$$

Scheduling algorithms for dynamic priorities

many algorithms are adaptations of static priority scheduling algorithms

example:

- Dynamic Sporadic Server

some algorithms were born for dynamic priorities:

- Total Bandwidth Server
- Total Bandwidth Server*
- Constant Bandwidth Server

Assumptions

concurrent scheduling of soft aperiodic tasks and
hard periodic tasks

assuming that

- periodic tasks are scheduled by EDF
- implicit deadlines (deadlines are equal to periods)
- full preemption
- for aperiodic tasks:
 - unknown arrival times
 - known computation times

Total Bandwidth Server

server design parameter:

- bandwidth (utilization) U_s

operating rules:

- an aperiodic task J arrives at time r_k
- the J task requires C_k time units to execute
- an absolute deadline d_k is calculated for J

$$d_k = \max(r_k, d_{k-1}) + \frac{C_k}{U_s}$$

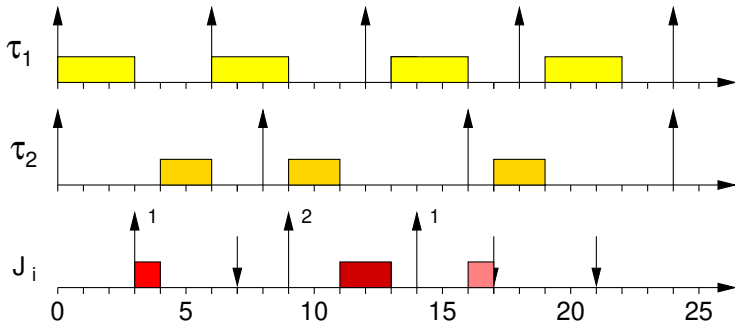
- being $d_0 = 0$ by definition
- J is scheduled by EDF considering the computed deadline d_k

TBS: example

$$\tau_1 = (3, 6)$$

$$\tau_2 = (2, 8)$$

$$U_s = 1 - U_p = 0.25$$



$$d_k = \max(r_k, d_{k-1}) + \frac{C_k}{U_s}$$

$$\max(3, 0) + \frac{1}{0.25} = 3 + 4 = 7$$

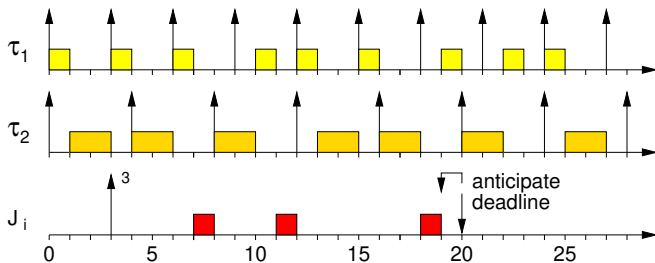
$$\max(9, 7) + \frac{2}{0.25} = 9 + 8 = 17$$

$$\max(14, 17) + \frac{1}{0.25} = 17 + 4 = 21$$

Total Bandwidth Server*

TBS* shortens the deadline of the aperiodic task J as much as possible

- the first assignment is done as in TBS
- the deadline can be shortened to the actual finishing time



$$\tau_1 = (1, 3)$$

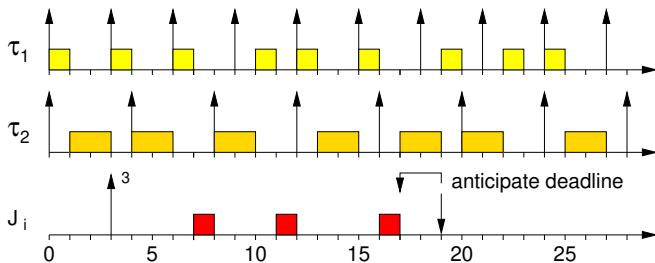
$$\tau_2 = (2, 4)$$

$$U_s = 1 - U_p = 0.1667$$

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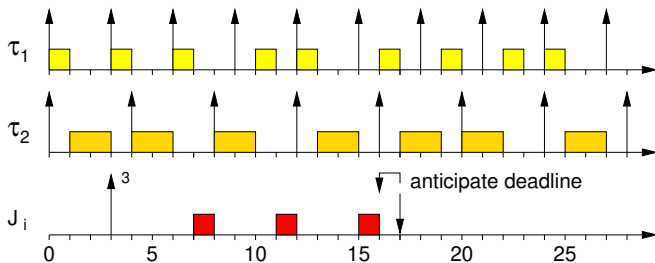
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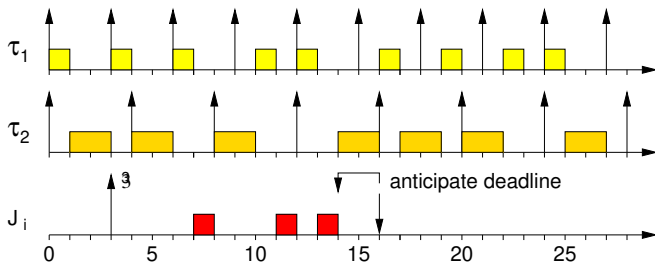
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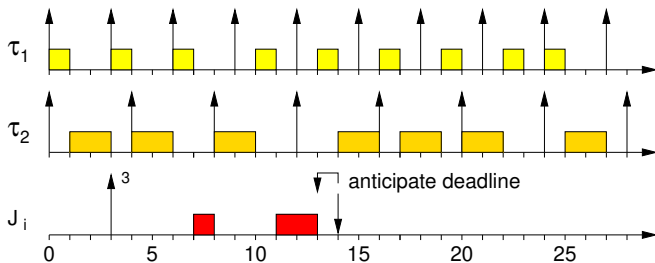
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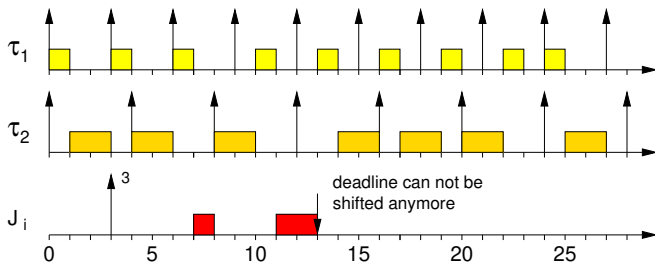
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Total Bandwidth Server*

the deadline is shortened
using an iterative process

being at iteration s :

- d_k^s is the deadline assigned to J_k
- f_k^s is the finishing time of J_k

the iterative shortening process is:

- at step $s + 1$ it is set $d_k^{s+1} = f_k^s$
- the process stops when $d_k^{s+1} = d_k^s$

Total Bandwidth Server*

computational issue

- the calculation of the worst-case finishing time may require to perform the schedule until the desired time
 - in many cases (e.g., high utilization of periodic tasks), this may lead to impractical computation times
-
- the finishing time f_k^S can be approximated
 - an upper bound is proved to exist
 - its calculation is fast enough to be used online

TBS*: optimality

Theorem

TBS* generates the absolute deadline of an aperiodic task such as its response time is minimized

therefore, TBS* is optimal
(in the sense of response time minimization)

Constant Bandwidth Server

- the CBS implements a bandwidth reservation scheme
- let U_s be the bandwidth assigned to the CBS
- the CBS never requires more than U_s to work

the server absolute deadline is based on the server bandwidth

- ... even in case of overload (overrun of aperiodic tasks)

the absolute deadline is postponed to achieve the constraint on the bandwidth assigned to the server

- performance in terms of response time for aperiodic tasks is similar to those of TBS

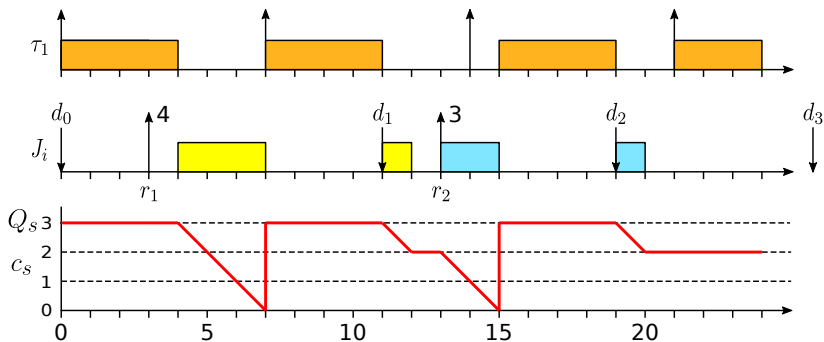
CBS: operating rules

- 1 maximum budget Q_s , period T_s and current budget c_s
- 2 server bandwidth: $U_s = Q_s/T_s$
- 3 at every time, the k -th calculated absolute deadline $d_{s,k}$ is the current deadline of the CBS
- 4 by definition $d_{s,0} = 0$
- 5 at each job $J_{i,j}$ it is assigned the absolute deadline $d_{i,j} = d_{s,k}$
- 6 the current budget c_s decreases of one unit for each time unit of execution
- 7 when $c_s = 0$ the budget is refilled (i.e., it is set $c_s = Q_s$), and a new absolute deadline is computed as $d_{s,k+1} = d_{s,k} + T_s$

CBS: operating rules

- 1 the server is *active* when there are pending aperiodic jobs, *idle* otherwise
- 2 when the **server is active**, a new aperiodic job $J_{i,j}$ is queued with arbitrary policy to the queue of pending requests
- 3 when the **server is idle** and a new aperiodic job $J_{i,j}$ is released:
 - if $c_s \geq (d_{s,k} - r_{i,j})U_s \Rightarrow$ compute a new absolute deadline $d_{s,k+1} = r_{i,j} + T_s$ and set $c_s = Q_s$
 - otherwise \Rightarrow schedule $J_{i,j}$ with the current absolute deadline $d_{s,k}$ and budget c_s
- 4 when **a job finishes**, the next one is served with absolute deadline $d_{s,k}$ and budget c_s
- 5 if no more tasks are present in the queue, the server becomes idle

CBS: example



$$c_s \geq (d_{s,0} - r_1)U_s \Rightarrow 3 \geq (0 - 3)0.375$$

$$c_s < (d_{s,2} - r_2)U_s \Rightarrow 2 < (19 - 13)0.375 = 2.25$$

$$\tau_1 = (7, 4)$$

$$Q_s = 3 \quad T_s = 8 \quad U_s = 0.375$$

CBS: schedulability analysis

- let U_p be the utilization of periodic tasks
- the utilization of a CBS is always $U_s = Q_s/T_s$ independently from the timing parameters of aperiodic jobs
- the system is schedulable iif $U_p + U_s \leq 1$
- since the budget c_s is never null, the CBS performs an automatic reclaiming of unused computing time in case of earlier termination of an aperiodic job

in case of m CBSs where the i -th server has utilization U_{s_i} , the system is schedulable iif

$$U_p + U_s \leq 1 \quad U_s = \sum_{i=1}^m U_{s_i}$$

Summary

TBS

- trivial operating rules
- good performance
- does not tolerate overloads

TBS*

- optimal response time
- higher complexity w.r.t. TBS
- trade-off can be established between response time and computational overhead

CBS

- bandwidth reservation in case of overload
- good performance (comparable with TBS)
- simple implementation